Method And Apparatus For Communicating Data Over Title:

A Bus According To Redefinable Configurations

Winkeler et al. Inventor(s): Express Mail. No. EV328618105US 66638/40337 Docket #

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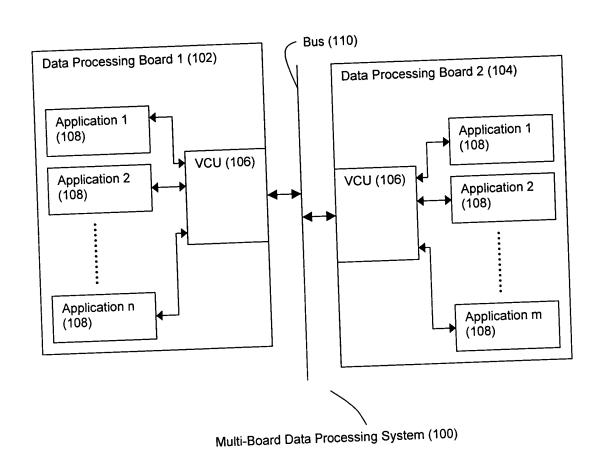


Figure 1

A Bus According To Redefinable Configurations

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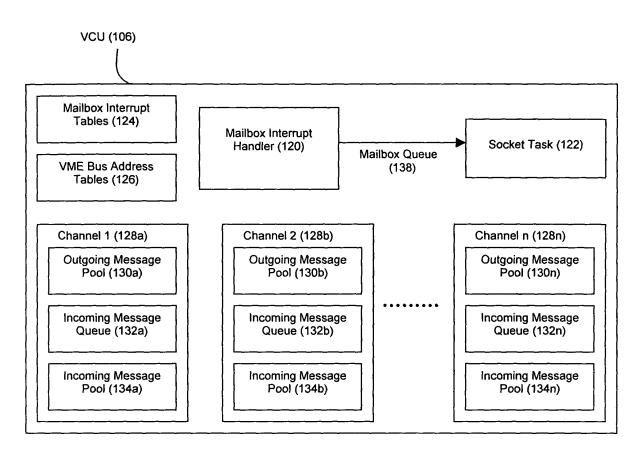


Figure 2

Title: Method And Apparatus For Communicating Data Over A Bus According To Redefinable Configurations

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Return Value:	Routine Name:	Arguments:	Description:
char*	vcuAllocateBuffer(.)	int channel	Allocates a buffer with proper caching properties, sized for the specified channel
unsigned int	vcuClearErrno(.)	none	Returns the first recorded VCU error # and clears it from the error system
void	vcuCommInit(.)	none	Starts the VCU service
void	vcuCommHalt(.)	none	Forcefully halts all VCU-related tasks
int	vcuDataSize(.)	int channel	Returns the maximum message size, in bytes, for the specified channel
unsigned int	vcuErrno(.)	none	Returns the first recorded VCU error #
int	vcuFree(.)	int channel, const char *data	Marks the specified memory location in the socket Rx memory pool as usable (see detailed description)
void	vcuFreeBuffer(.)	int channel, char *buffer	Frees a buffer allocated with the vcuAllocateBuffer(.) routine
int	vcuHasPushQueueMessage(.)	int channel	Returns the number of messages in the push queue for the specified channel
int	vcuHasRxQueueMessage(.)	int channel	Returns the number of messages queued for the specified channel
int	vculfaceHasRxDataQueueMessage(.)	none	Returns the number of vcuRecv(.) replies queued
int	vculfaceHasRxRqstQueueMessage(.)	none	Returns the number of vcuRecv(.) calls queued
int	vculfaceHasTxQueueMessage(.)	поле	Returns the number of vcuSend(.) calls queued
int	vculfaceHasTxReplyQueueMessage(.)	none	Returns the number of vcuSend(.) replies queued (used for push configs)
int	vculfaceHasTxStatusQueueMessage(.)	попе	Returns the number of vcuSend(.) status messages queued
int	vculsMemPairPoolEmpty(.)	none	Returns 0 if the mem pair pool (used for push configs) is not empty and a non-zero value if it is empty
int	vculsRxPoolEmpty(.)	int channel	Returns 0 if the receive pool for the specified channel is not empty and a non-zero value if it is empty

Figure 3(a)

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Return Value:	Routine Name:	Arguments:	Description:
int	vculsTxPoolEmpty	int channel	Returns 0 if the transmit pool for the specified channel is not empty and a non-zero value if it is empty
int	vcuPing(.)	int destination	Checks that a remote board is reachable via VCU. If more than one bit is set, a table is printed
void	vcuPrintChannelInfo(.)	int channel	Prints out the configuration information for the specified channel. If the argument is 0 (default), a table is printed
void	vcuPrintDebug(.)	int debugLevel	Triggers a printout of debugging data
int	vcuQueryForConfig(.)	int channel	Returns the configuration of the channel for internal VCU use (defined in vcuDefines.h)
unsigned int	vcuRecentErrno(.)	none	Returns the last recorded VCU error number
int	vcuRecv(.)	See Detailed Description	See Detailed Description
int	vcuRequestErrno(.)	int destination	Receives the VCU error # from a remote board. If more than one bit is set, a table is printed
int	vcuRequestTestPattern(.)	int destination, int channel, int msgSize	Requests a remote board to send a pre- defined test pattern of a requested size, and prints out success or error of delivery
int	vcuSend(.)	See Detailed Description	See Detailed Description

# Figure 3(b)

Debug Level:	Description:
1	Prints out the use status of all Rx memory pools
2	Prints out the use status of all Tx memory pools
3	Prints out the use status of all Rx and Tx memory pools
4	Prints out detailed information about each slot of all Rx memory pools
5	Prints out detailed information about each slot of all Tx memory pools
6	Prints out detailed information about each slot of all Rx and Tx memory pools
7	Prints out the status of all Rx queues
8	Prints out the status of all push queues
9	Prints out detailed information about each slot of memPair memory pool
101	Prints out internal timing information if the system has been instrumented for timing

Figure 4

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Configuration Type:	Sender Side:	Receiver Side:
Copy on Send	while(RUNNING){    vcuSend(dest, chan, data, size); }	while(RUNNING){  vcuRecv(chan, pAddr, size);  //Handle message at pAddr  //(size in bytes length)  vcuFree(chan, pAddr); }
Copy to Pool on Receive	while(RUNNING){ vcuSend(dest, chan, data, size); }	white(RUNNING){  vcuRecv(chan, pAddr, size);  //Handle message at pAddr  //(size in bytes length)  vcuFree(chan, pAddr); }
Copy to Buffer on Receive	while(RUNNING){    vcuSend(dest, chan, data, size); }	buf = vcuAllocateBuffer(chan) while(RUNNING){     vcuRecv(chan, buf, size);     vcuFree(chan, buf); } vcuFreeBuffer(chan, buf); }
Push to Pool on Receive	int pAddr = 0x0 int id = UNIQUE_VALUE while(RUNNING){     vcuSend(dest, chan, data, size, pAddr,	while(RUNNING){  vcuRecv(chan, pAddr, size);  //Handle message at pAddr  //(size in bytes length)  vcuFree(chan, pAddr); }
Push to Buffer on Receive	int pAddr = 0x0 int id = UNIQUE_VALUE while(RUNNING){     vcuSend(dest, chan, data, size, pAddr,     id);     //Changes in pAddr indicated when data     //was read }	buf = vcuAllocateBuffer(chan) while(RUNNING){     vcuRecv(chan, buf, size);     vcuFree(chan, buf); } vcuFreeBuffer(chan, buf);
Queue on Send	while(RUNNING){   vcuSend(dest, chan, data, size); }	buf = vcuAllocateBuffer(chan) while(RUNNING){     vcuRecv(chan, buf, size);     vcuFree(chan, buf); } vcuFreeBuffer(chan, buf);
Copy to Self	while(RUNNING){    vcuSend(dest, chan, data, size); }	while(RUNNING){  vcuRecv(chan, pAddr, size);  //Handle message at pAddr  //(size in bytes length)  vcuFree(chan, pAddr); }
Overwrite on Send	while(RUNNING){   vcuSend(dest, chan, data, size); }	while(RUNNING){ vcuRecv(chan, pAddr, size); //Handle message at pAddr //(size in bytes length) }

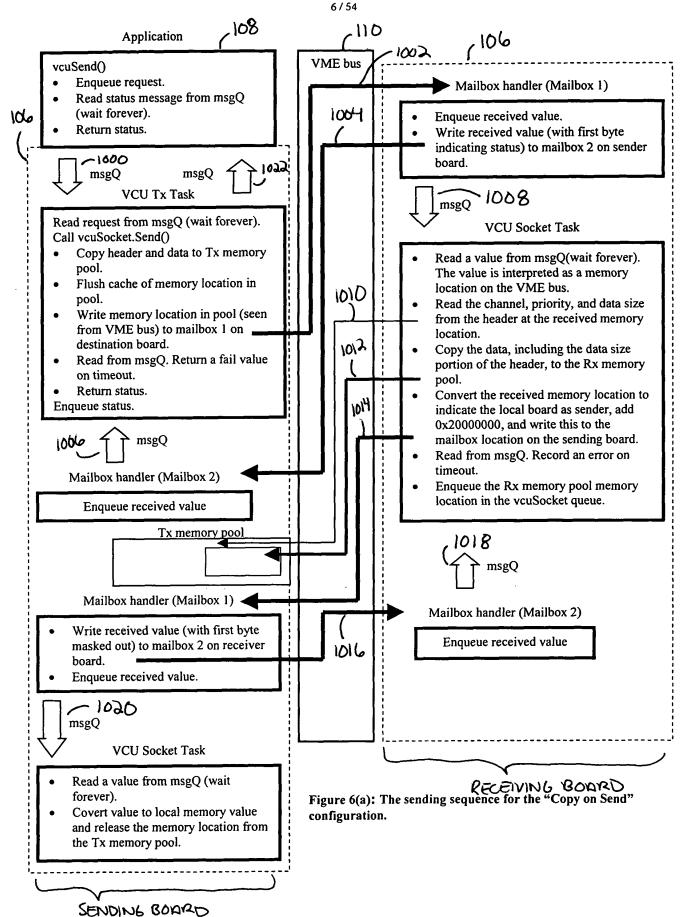
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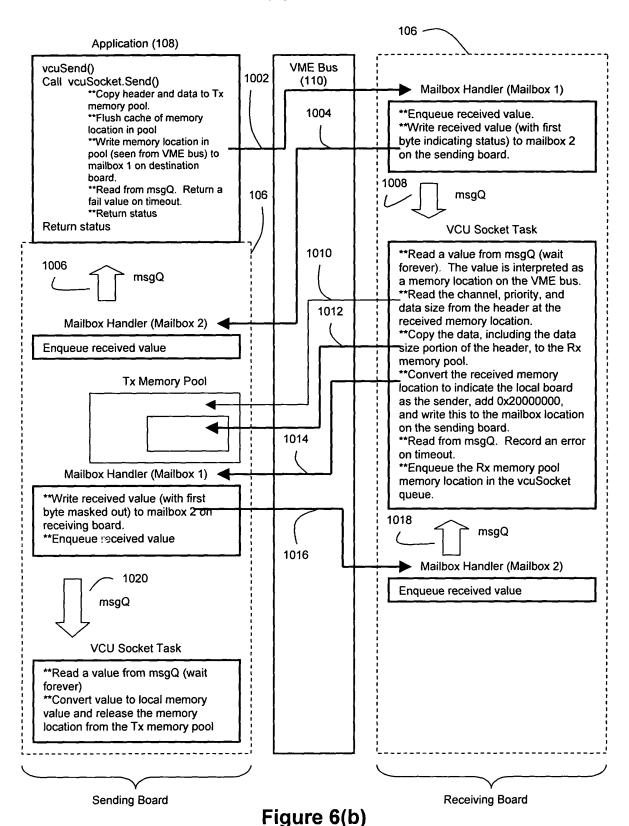
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(sending sequence for copy on send configuration with VCU Tx Task removed)

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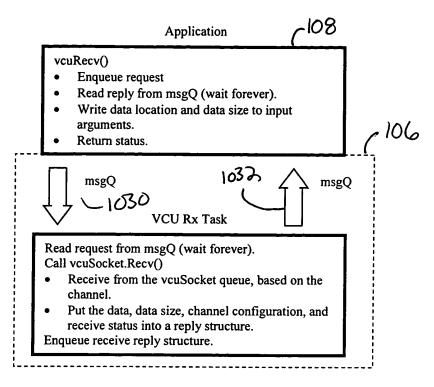


Figure 7(a): The receiving sequence for the "Copy on Send" configuration.

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#### Application (108)

### vcuRecv()

\*\*Call vcuSocket.Recv()

\*\*Receive from the vcuSocket queue,

based on the channel
\*\*Write the value received into the appropriate argument.

\*\*Return status.

\*\*Set the message size to the value in the header of the message stored at the location indicated in the return value. \*\*Set the message location in the input

argument

Figure 7(b) (receiving sequence for the copy on send configuration with the VCU Rx Task removed)

A Bus According To Redefinable Configurations Inventor(s): Winkeler et al. Express Mail. No. EV328618105US Docket # 66638/40337 10/54 108 Application VME bus vcuSend() Enqueue request. 110 Read status message from msgQ (wait forever). 106 Return status. 1040 msgQ VCU Tx Task 1048 Read request from msgQ (wait forever). Call vcuSocket.Update() 106 Copy header and data to Tx memory pool. 1042 Flush cache of memory location in pool. Mailbox handler (Mailbox 1) Write memory location in pool (seen from VME bus) to mailbox 1 on Write received value (with first byte destination board. indicating status) to mailbox 2 on sender Read from msgQ. Return a fail value board. on timeout. 104 Enqueue received value. Return status Enqueue status. -1050 msgQ1046 msgQ VCU Socket Task Mailbox handler (Mailbox 2) Read a value from msgQ(wait forever). Enqueue received value. The value is interpreted as a memory location on the VME bus. Read the channel and priority from the header at the received memory location. Tx memory pool Enqueue the memory location in the vcuSocket queue.

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SENDING Figure 8(a): The sending sequence for the "Copy to Pool on Recv" configuration. RECEIVING BOARD

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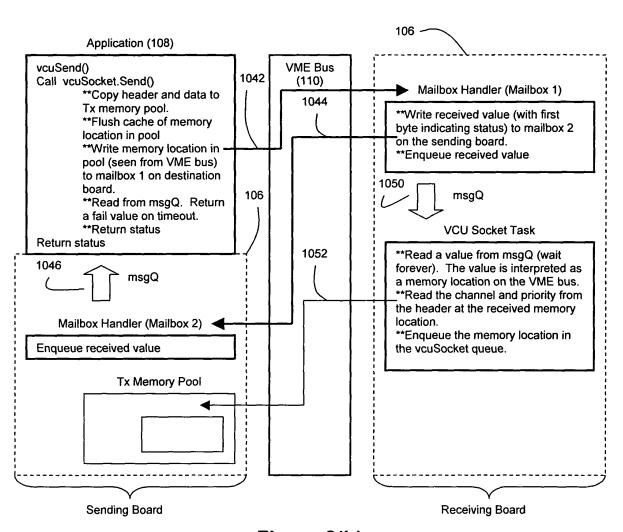
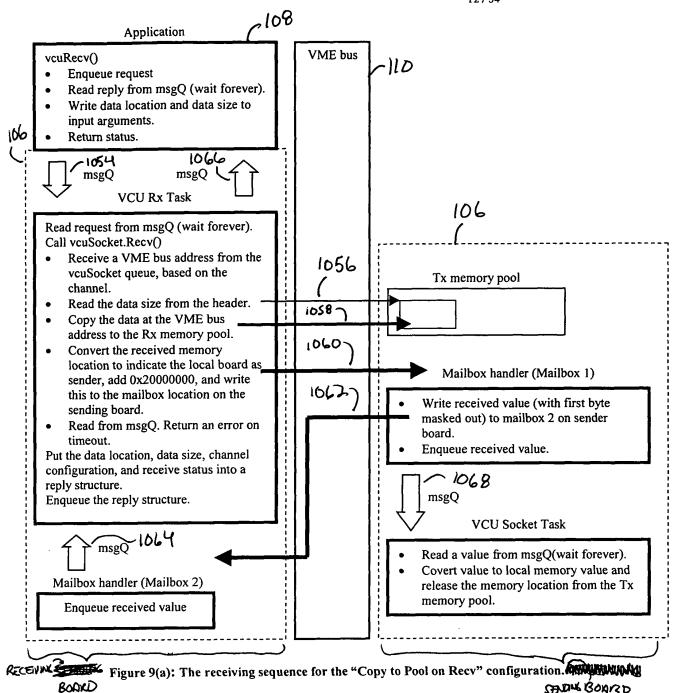


Figure 8(b)
(sending sequence for copy to pool on receive configuration)

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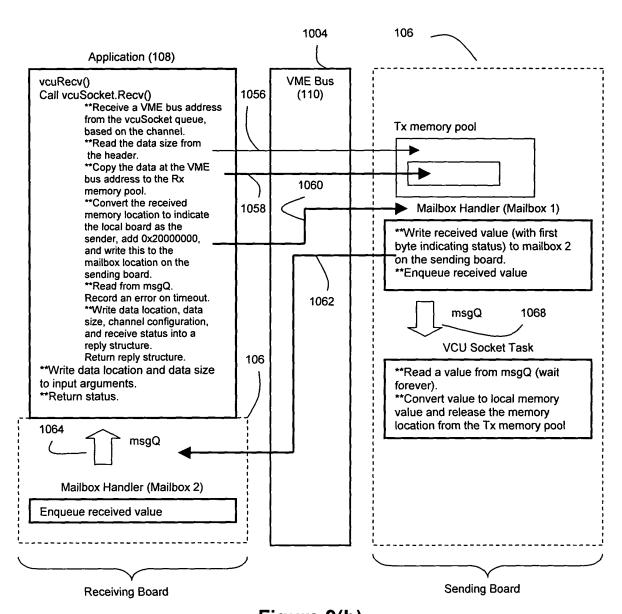


Figure 9(b)
(receiving sequence for copy to pool on receive configuration)

Winkeler et al. Inventor(s): Express Mail. No. EV328618105US Docket # 66638/40337 14/54 C108 Application vcuSend() VME bus 110 Enqueue request Read response from msgQ (wait forever) Update the memory location value in the input argument. 106 Return status. msgQ msgQ VCU Tx Task 106 Read request from msgQ (wait forever). Call vcuSocket.Update() Try to lock specified location in Tx memory pool. If fails, take a new Mailbox handler (Mailbox 1) memory location and lock it. Copy data to Tx memory pool. Write received value (with first byte Flush cache of memory location in indicating status) to mailbox 2 on sender board. Unlock location in Tx memory pool. Enqueue received value. If using a new memory location (initial lock failed), write memory location in pool (seen from VME bus) msgQto mailbox 1 on destination board. Read from msgQ. Return a fail value VCU Socket Task on timeout. Put the memory location and transmission Read a value from msgQ(wait forever). status into a reply structure. The value is interpreted as a memory Enqueue the reply structure. location on the VME bus. Read the channel and priority from the header at the received memory location. msgQ Enqueue the memory location in the vcuSocket queue. Mailbox handler (Mailbox 2) Enqueue received value. Tx memory pool

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Figure 10: The sending sequence for the "Push to Pool on Recv" configuration

SENDING BOARD

A Bus According To Redefinable Configurations Inventor(s): Winkeler et al. Express Mail. No. EV328618105US Docket # 66638/40337 15/54 ط10م 108 Application VME bus Mailbox handler (Mailbox 1) vcuRecv() Enqueue request Write received value (with first byte Read reply from msgQ (wait indicating status) to mailbox 2 on forever). receiver board. Write data location and data size to Enqueue received value. input arguments. 106 Return status msgQ msgQ msgQ VCU Socket Task VCU Rx Task Read a value from msgQ(wait forever). Read request from msgQ (wait forever). Subtract 0x40000000 from the Call vcuSocket.Recv() received value to get a VME bus Receive a VME bus address from the address. vcuSocket queue, based on the Read source and destination memory channel. locations, channel, and ID from across Take a memory location in the Rx VME bus. memory pool. Lock the local (source) memory Write the VME bus address, the location, which is in the Tx memory local address (as seen from the VME pool. bus), an ID, and the channel to a Write the data size across the VME location in the mem pair memory pool. Copy data from source to destination. Add 0x40000000 to the mem pair Release the local (source) memory memory address and write this to the location. Clear the owner ID. Unlock mailbox location on the sending the memory location. board. Logically AND a board-specific Read from msgQ. Return a fail value value, a bit-shifted version of the ID on timeout. read from across the VME bus, and Read response from Push msgQ (wait the channel. Write the result to the forever). Verify that response mailbox location on the receiving matches ID. Read the data size from the mem pair Read from msgQ. Record a fail value memory pool, then release the slot in on timeout. the pool. Put the data location, data size, channel configuration, and receive status into a msgQ reply structure. Enqueue the reply structure. ► Mailbox handler (Mailbox 2) msgQ Enqueue received value Mailbox handler (Mailbox 2) Enqueue received value Figure 11(a) JENDING Continued on next page

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RECEIVING BOARD

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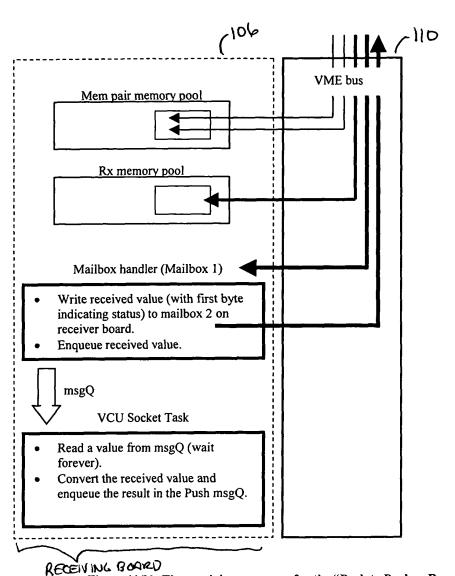
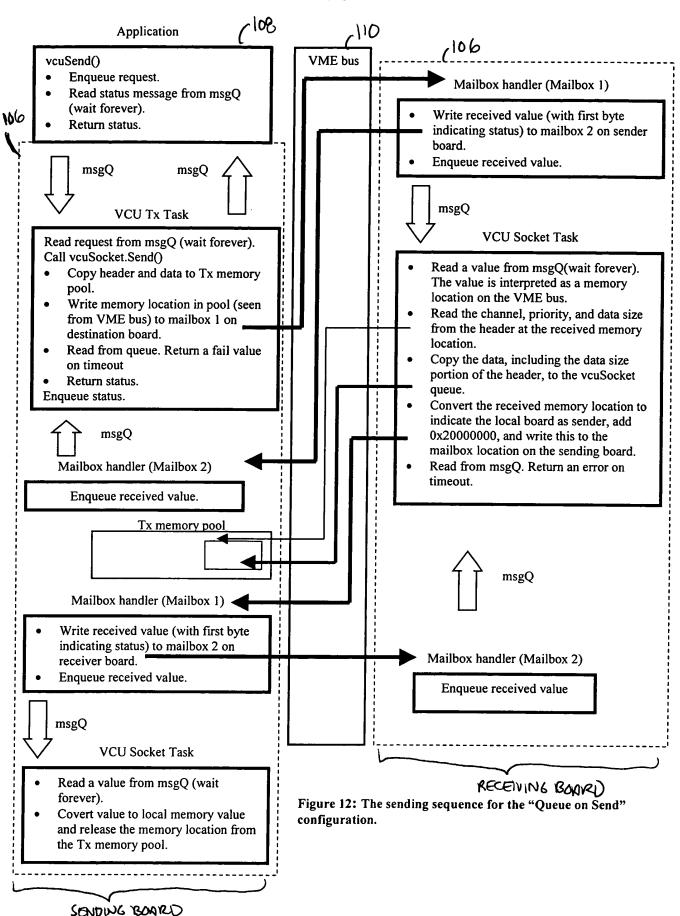


Figure 11(b): The receiving sequence for the "Push to Pool on Recv" configuration.

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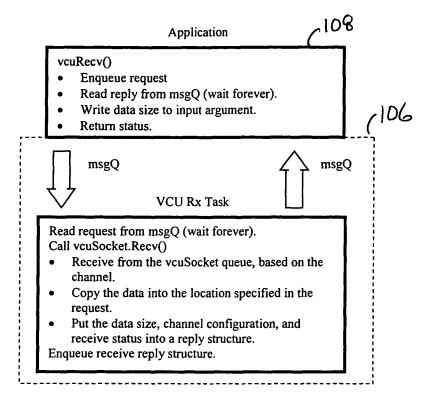


Figure 13: The receiving sequence for the "Queue on Send" configuration.

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19/54 -108 Application vcuSend() Enqueue request. Read status message from msgQ (wait forever). Return status. 106 msgQ msgQ VCU Tx Task Read request from msgQ (wait forever). Call vcuSocket.SendToSelf() Copy header and data to Rx memory pool. Enqueue the Rx memory pool memory location in the vcuSocket Return status. Enqueue status.

Figure 14: The sending sequence for the "Copy to Self" configuration.

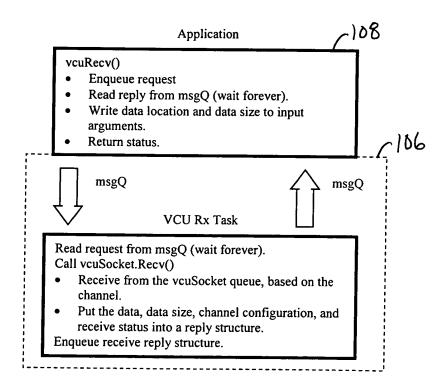


Figure 15: The receiving sequence for the "Copy to Self" configuration.

Express Mail. No. EV328618105US Docket # 66638/40337 20/54 - 10B Application 106 VME bus vcuSend() Enqueue request. Mailbox handler (Mailbox 1) Read status message from msgQ (wait forever). 106 Enqueue received value. Return status. Write received value (with first byte indicating status) to mailbox 2 on sender msgQ msgQ VCU Tx Task msgQ Read request from msgQ (wait forever). VCU Socket Task Call vcuSocket.Send() Copy header and data to Tx memory Read a value from msgQ(wait forever). pool. The value is interpreted as a memory Flush cache of memory location in location on the VME bus. pool. Read the channel, priority, and data size Write memory location in pool (seen from the header at the received memory from VME bus) to mailbox 1 on location. destination board. Copy the data, including the data size Read from msgQ. Return a fail value portion of the header, to the back buffer on timeout. of the double buffer. Return status. Convert the received memory location to Enqueue status. indicate the local board as sender, add 0x20000000, and write this to the msgQ mailbox location on the sending board. Read from msgQ. Record an error on timeout. Mailbox handler (Mailbox 2) Enqueue received value Tx memory pool Mailbox handler (Mailbox 1) Mailbox handler (Mailbox 2) Write received value (with first byte Enqueue received value masked out) to mailbox 2 on receiver board. Enqueue received value. msgQ VCU Socket Task Read a value from msgQ (wait RECEIVING BOOMS forever). Figure 16: The sending sequence for the "Overwrite on Send" Covert value to local memory value configuration. and release the memory location from the Tx memory pool.

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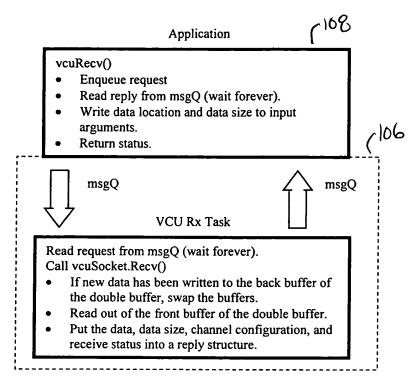


Figure 17: The receiving sequence for the "Overwrite on Send" configuration.

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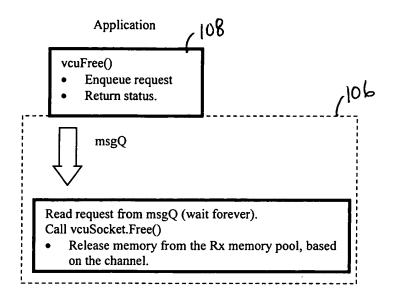
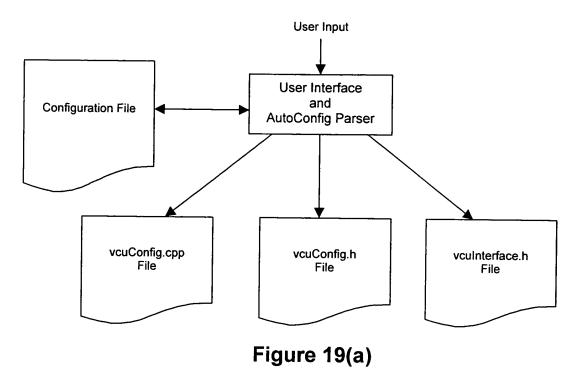
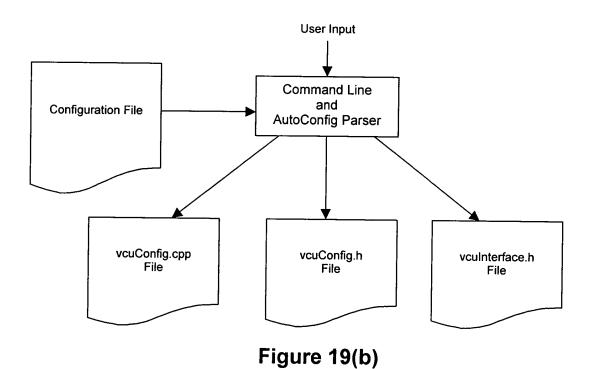


Figure 18: The freeing sequence for the receiver-side memory pool.

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	VCU Configuration File Grammar: Backus-Naur Form (BNF)
	Top Level:
	<config_file>::=,channel_section&gt; [<include_section>] [<handler_section>] [misc_section&gt;]</handler_section></include_section></config_file>
Description:	The configuration file should contain a channel declaration section and may optionally contain entries for include files, handler files, and other miscellaneous parameters.
	Channel Declaration Section:
	<pre><channel_section>::=Channels number <channel_statements></channel_statements></channel_section></pre>
Description:	The channel declaration should begin with the keyword "Channels" followed by a number representing the number of channels in the system. This is then followed by said number of channel declaration statements.
	Channel Declaration Statements:
	<pre><channel_statements>::=<channel_statement>   <channel_statement> <channel_statements></channel_statements></channel_statement></channel_statement></channel_statements></pre>
_	<pre><channel_statement>::=Chan number <channel_data_type> channel_name <channel_type></channel_type></channel_data_type></channel_statement></pre>
	<pre><channel_data_type>::=[struct   class] custom_type   untyped byte_count</channel_data_type></pre>
	<pre><channel_type>::=recvbuf   send   pushbuf  recvpool   pushpool  queue   self  overwrite   qself</channel_type></pre>
Description:	A channel statement provides the channel <i>number</i> followed by the channel data type which may be a structure or class of user-defined <i>custom_type</i> , or an untyped string of <i>byte_count</i> bytes. The last two tokens in a channel statement should be the user-defined <i>channel_name</i> and the channel_type. There also should be as many channel statements as the number of channels declared in the beginning of the channel declaration section.
	Include File Section:
	<include_section>::= Include number <include_statements></include_statements></include_section>
	<include_statements>::=,include_statement&gt;   <include_statement> <include_statements></include_statements></include_statement></include_statements>
	<include_statement>::= Include include_file</include_statement>
Description:	The include file section provides a number of filenames that should be "included" by the file vculnterface.h generated by the VCU configuration utility. The section must begin with the keyword "Include" followed by a number representing the number of include files in the configuration file. This is then followed by said number of include statements. Each include statement starts with the keyword "Include" and is followed by the filename include_file which should be "included" by vculnterface.h.
	Handler File Section:
	<handler_section>::=Handlers number <handler_statements></handler_statements></handler_section>
	<handler_statements>::=<handler_statement>   <handler_statement> <handler_statements></handler_statements></handler_statement></handler_statement></handler_statements>
	<handler_statement>::=Hndlr handlr_file</handler_statement>
Description:	The handler file section provides a number of filenames that should be "included" by the file vcuConfig.cpp generated by the VCU configuration utility. The section must begin with the keyword "Handlers" followed by a number representing a number of handler files in the configuration file. This is then followed by said number of handler statements. Each handler statement starts with the keyword "Handler" and is followed by the filename handler_file which should be "included" by the vcuConfig.cpp file.

Figure 20(a)

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	VCU Configuration File Grammar: Backus-Naur Form (BNF) (cont.)
	Miscellaneous Parameters Section:
	<misc_section>::=[<pool_parameters] [<single_parameters="">] [<multiple_parameters>]</multiple_parameters></pool_parameters]></misc_section>
<sìı< td=""><td>ngle parameters&gt;::=[<ackmailbox_parameter>] [<autoackoff_parameter>] [<autoackon_parameter>] [datamailbox_parameter&gt;] [<debugon_parameter>] [<mailboxqueuesize_parameter>] [<mempairpoolsize_parameter>] [<partitionaddr_parameter>] [<partitionfactor_parameter>] [<slavewinsize_parameter>] [<taskpriority_parameter>]</taskpriority_parameter></slavewinsize_parameter></partitionfactor_parameter></partitionaddr_parameter></mempairpoolsize_parameter></mailboxqueuesize_parameter></debugon_parameter></autoackon_parameter></autoackoff_parameter></ackmailbox_parameter></td></sìı<>	ngle parameters>::=[ <ackmailbox_parameter>] [<autoackoff_parameter>] [<autoackon_parameter>] [datamailbox_parameter&gt;] [<debugon_parameter>] [<mailboxqueuesize_parameter>] [<mempairpoolsize_parameter>] [<partitionaddr_parameter>] [<partitionfactor_parameter>] [<slavewinsize_parameter>] [<taskpriority_parameter>]</taskpriority_parameter></slavewinsize_parameter></partitionfactor_parameter></partitionaddr_parameter></mempairpoolsize_parameter></mailboxqueuesize_parameter></debugon_parameter></autoackon_parameter></autoackoff_parameter></ackmailbox_parameter>
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Description:	Single parameter options should occur only once per configuration file, while multiple parameter options may occur several times, usually on a per-channel basis.
Pod	ol Parameters:
	<pre><pool_parameters>::=BoardCount number [<norxpool_parameters>] [<notxpool_parameters>]</notxpool_parameters></norxpool_parameters></pool_parameters></pre>
	<norxpool_parameters>::=<norxpool_parameter> <norxpool_parameter><norxpool_parameters></norxpool_parameters></norxpool_parameter></norxpool_parameter></norxpool_parameters>
	<notxpool_parameters>::=<notxpool_parameter> <notxpool_parameter><notxpool_parameters></notxpool_parameters></notxpool_parameter></notxpool_parameter></notxpool_parameters>
	<pre><norxpool_parameter>::=NoRxPool chan_number board_processor_number</norxpool_parameter></pre>
	<notxpool_parameter>::=NoTxPool chan_number board_processor_number</notxpool_parameter>
Description:	The pool parameters indicate which, if any, channel/board combinations should not allow receiving or transmitting respectively. The parameter list begins with the "BoardCount" keyword followed by the <i>number</i> of boards, or system processors, in the system. This is followed by one or more "NoRxPool" or "NoTxPool" keywords which tell the system which channel/board pairings, indicated by <i>chan_number</i> and <i>board_processor_number</i> , should not allow receiving and transmitting respectively.
Ack	Mailbox Parameter:
	<ackmailbox_parameter>::=AckMailbox number</ackmailbox_parameter>
Description:	This option indicates which mailbox, represented by number, should be used for automatic acknowledgements. This value must be different from the DataMailbox value, and defaults to ∠.
Aut	oAckOff Parameter:
	<autoackoff_parameter>::=AutoAckOff</autoackoff_parameter>
Description:	This option indicates that auto acknowledgement should not be used in the VCU system.
Aut	oAckOn Parameter:
	<autoackon_parameter>::=AutoAckOn floating_point_number</autoackon_parameter>
Description: indicates the t	This option turns on the automatic acknowledgement feature of the VCU system. The floating_point_number meout value in seconds before the message is assumed lost. This value defaults to 0.05 seconds.
Data	aMailbox Parameter:
	<datamailbox_parameter>::=DataMailbox <i>number</i></datamailbox_parameter>
Description:	This indicates which mailbox, represented by number, should be used for inter-board communication. This value must be different from the AckMailbox value, and defaults to 1.

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	VCU Configuration File Grammar: Backus-Naur F rm (BNF) (cont.)
	Miscellaneous Parameters Section (c nt.):
Debu	g Parameter:
	<debugon_parameter>::=DebugOn</debugon_parameter>
Description:	This option turns on the printing to console all values received in the data mailbox interrupt.
Mailb	ox Queue Size Parameter:
	<mailboxqueuesize_parameter>::=MailboxQueueSize size</mailboxqueuesize_parameter>
Description:	This option sets the size of the message queue leaving the mailbox ISR. The default size is 8.
Memo	ory Pair Pool Size Parameter:
	<mempairpoolsize_parameter>::=MemPairPoolSize size</mempairpoolsize_parameter>
Description:	This option sets the <i>size</i> of the memory pool for memory pairs used by all "push" channels on the board. The default size is 8.
Partit	ion Address Parameter:
	<pre><partitionaddr_parameter>::=PartitionAddress addr</partitionaddr_parameter></pre>
Description:	This option sets the location of the memory partition created by the VCU for VME bus accessibility to the value specified in addr.
Partit	ion Factor Parameter:
	<pre><partitionfactor_parameter>::=PartitionFactor factor</partitionfactor_parameter></pre>
Description:	This option sets the factor used in setting the size of the partition.
Slave	Window Size Parameter:
	<slavewinsize_parameter>::=SlaveWindowSize half   SlaveWindowSize full</slavewinsize_parameter>
Description: 0x04000000 and	This option sets the size of the VME slave windows for boards in the system. "Half" sets the size to "full" to 0x08000000, with the default being half.
Task i	Priority Parameter:
	<taskpriority_parameter>::=TaskPriority priority</taskpriority_parameter>
Description:	This option sets the <i>priority</i> for the VCU socket task.
DMA I	Parameter:
	<dma_parameter>::=DMA chan_number</dma_parameter>
Description:	This option turns forces the indicated chan_number to always use DMA.
DMA S	Start Parameter:
	<pre><dmastart_parameter>::=DMAStart chan_number message_size</dmastart_parameter></pre>
Description:	This option forces the indicated <i>chan_number</i> to always use DMA for messages that have sizes that are qual to <i>message_size</i> bytes.

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	VCU Configuration File Grammar: Backus-Naur Form (BNF) (cont.)	
Misc Ilaneous Parameters Section (cont.):		
Even	t Parameter:	
	<pre><event_parameter>::=Event chan_number event_handler</event_parameter></pre>	
Description:	This option specifies the routine (event_handler) to be called when a board receives a message for the channel indicated by channel_number.	
Guar	anteed Delivery Parameter:	
	<pre><guaranteeddel_parameter>::=GuaranteedDelivery chan_number</guaranteeddel_parameter></pre>	
Description:	This option forces the indicated <i>chan_number</i> to block on certain queue and pool overflows rather than risk losing the message.	
Rece	ive Pool Size Parameter:	
	<rxpoolsize_parameter>::=RxPoolSize chan_number size</rxpoolsize_parameter>	
Description:	This option sets the size of the receiving memory pool for the indicated chan_number. The default value is 8.	
Recei	ive Queue Size Parameter:	
	<rxqueuesize_parameter>::=RxQueueSize chan_number size</rxqueuesize_parameter>	
Description:	This option sets the <i>size</i> of the receiving message queue for the indicated <i>chan_number</i> . The default value is 8.	
Trans	mit Pool Size Parameter:	
· · · · · · · · · · · · · · · · · · ·	<txpoolsize_parameter>::=TxPoolSize chan_number size</txpoolsize_parameter>	
Description:	This option sets the <i>size</i> of the transmitting memory pool for the indicated <i>chan_number</i> . The default value is 8.	

Figure 20(d)

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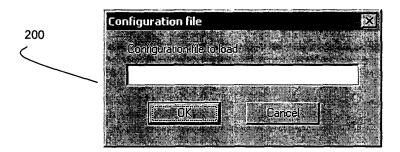


Figure 21: Initial Dialog Window for the GUI

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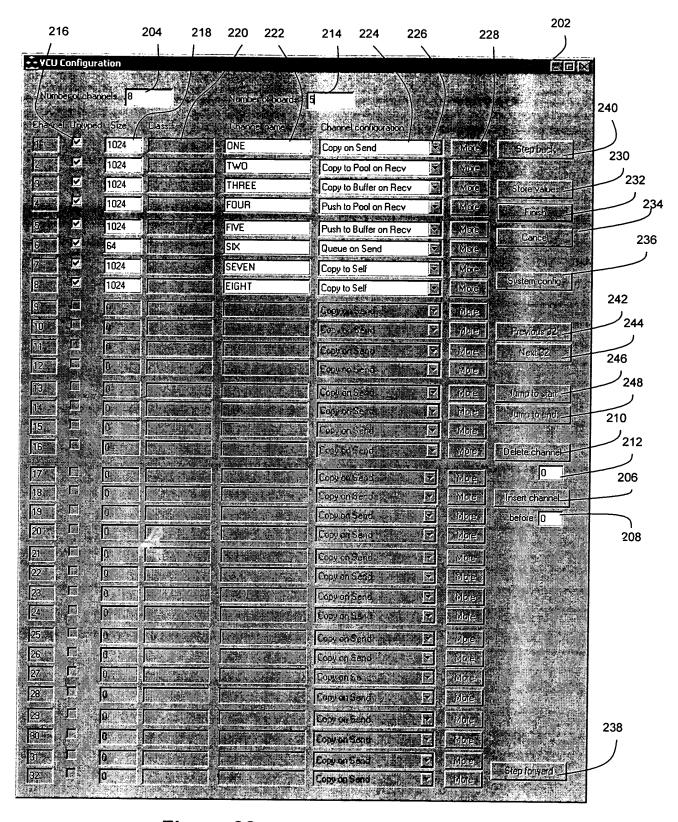


Figure 22: Primary dialog window of the GUI

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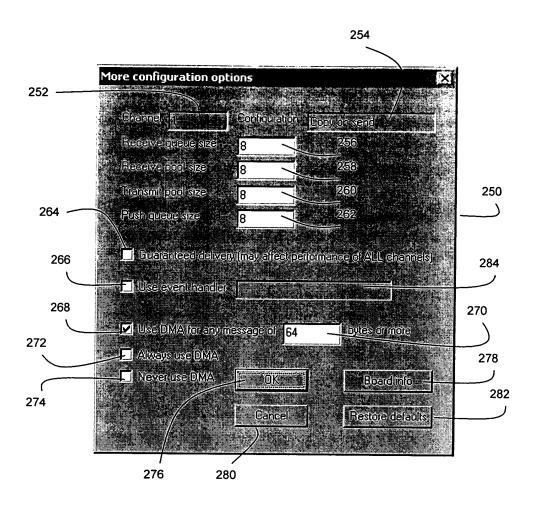


Figure 23: The "More configuration options" dialog window

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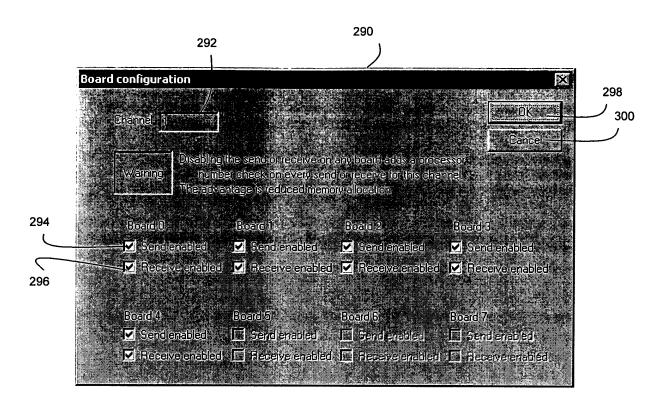


Figure 24: The "Board configuration" dialog window

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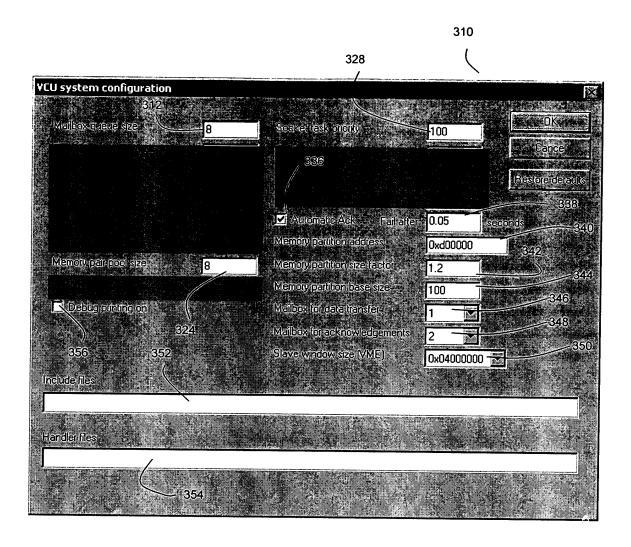


Figure 25: The "VCU system configuration" dialog window

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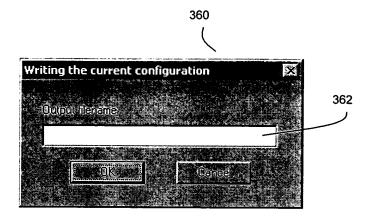


Figure 26: The "Writing the current configuration" dialog window

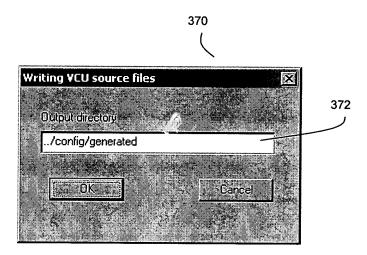


Figure 27: The "Writing the VCU source files" dialog window

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Configuration:	Receive Queue Size:	Receive Pool Size:
Copy on Send	Maximum difference between the number of remote vcuSend() and local vcuRecv() calls. On overflow, the message is lost or the entire system blocks	Maximum difference between the number of remote vcuSend() and local vcuRecv() calls. On overflow, the message is lost or the entire system blocks
Copy to Pool on Receive	Maximum difference between the number of remote vcuSend() and local vcuRecv() calls. On overflow, the message is lost or the entire system blocks.	Maximum difference between the number of vcuRecv() and vcuFree() calls. On overflow, vcuRecv() returns an error
Copy to Buffer on Receive	Maximum difference between the number of remote vcuSend() and local vcuRecv() calls. On overflow, the message is lost or the entire system blocks	N/A
Push to Pool on Receive	Maximum number of remote sources of vcuSend() calls (each source has a unique ID and keeps track of the transmit pool address it is using). On overflow, the message is lost or the entire system blocks.	Maximum difference between the number of vcuRecv() and vcuFree() calls. On overflow, vcuRecv() returns an error
Push to Buffer on Receive	Maximum number of remote sources of vcuSend() calls (each source has a unique ID and keeps track of the transmit pool address it is using). On overflow, the message is lost or the entire system blocks.	N/A
Queue on Send	Maximum difference between the number of remote vcuSend() and local vcuRecv() calls. On overflow, the message is lost or the entire system blocks	N/A
Copy to Self	Maximum difference between the number of vcuSend() and vcuRecv() calls. On overflow, vcuSend() returns an error	Maximum difference between the number of vcuRecv() and vcuFree() calls. On overflow, vcuRecv() returns an error
Overwrite on Send	N/A	N/A

Figure 28

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Configuration:	Transmit Pool Size:	Push Queue Size:
Copy on Send	Maximum number of local sources of vcuSend() calls. On overflow, vcuSend() returns an error.	0
Copy to Pool on Receive	Maximum difference between the number of local vcuSend() and remote vcuRecv() calls. On overflow, vcuSend() returns an error.	0
Copy to Buffer on Receive	Maximum difference between the number of local vcuSend() and remote vcuRecv() calls. On overflow, vcuSend() returns an error.	0
Push to Pool on Receive	Twice the number of local sources of vcuSend() calls (each source has a unique ID and keeps track of the transmit pool address it is using). On overflow, vcuSend() returns an error.	Maximum number of local sources of vcuSend() calls. On overflow, vcuSend() returns an error
Push to Buffer on Receive	Twice the number of local sources of vcuSend() calls (each source has a unique ID and keeps track of the transmit pool address it is using). On overflow, vcuSend() returns an error.	Maximum number of local sources of vcuSend() calls. On overflow, vcuSend() returns an error
Queue on Send	Maximum number of local sources of vcuSend() calls. On overflow, vcuSend() returns an error.	0
Copy to Self	N/A	0
Overwrite on Send	Maximum number of local sources of vcuSend() calls. On overflow, vcuSend() returns an error.	0

Figure 29

382 384 -380 Channels 6 **BUTTON\_PRESS\_CHANNEL** Chan 1 buttonPress recvbuf Chan 2 class Eventinfo EVENT\_INFO\_CHANNEL send Chan 3 struct NavData NAV\_DATA\_CHANNEL pushbuf BIG\_RAW\_DATA\_CHANNEL Chan 4 untyped 1024 recvpool Chan 5 untyped 32 SMALL\_RAW\_DATA\_CHANNEL pushpool Chan 6 untyped SMALL\_FAST\_CHANNEL queue Includes 3 Incl NavData.h Incl EventInfo.h Incl ButtonPress.h MailboxQueueSize 10 **DMA** 1 NO\_DMA 2 **RxPoolSize** 1 10

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**TxPoolSize** 

1

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Figure 30: An example configuration file

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Keyword: Parameters:		Meaning:	
AckMailbox	1	"AckMailbox" indicates the mailbox used for the automatic acknowledgement. It should differ from the "DataMailbox" value. The default value is 2.	
AutoAckOff	0	"AutoAckOff" turns off the automatic acknowledgement system for the VCU. With auto ack turned off, the VCU uses only one mailbox interrupt per board, but cannot guarantee that messages will not be lost.	
AutoAckOn	1	"AutoAckOn" turns on the automatic acknowledgement system for the VCU. The parameter sets the delay for an acknowledgement from the receiving board before the message is assumed lost. The default value for the parameter is 0.05 (in seconds).	
BoardCount	1	"BoardCount" specifies the number of boards in the system. This value is only used in conjunction with "NoRxPool" and "NoTxPool".	
Chan	4 (or 5)	"Chan" specifies a data type, channel name, and configuration type for one channel. Specifying "Chan" a second time for a channel resets the DMA size specs, even if they were changed from default by a "DmaStart" line. "Chan 0" is not allowed. Also, "Chan" cannot be specified before "Channels".	
Channels	1	"Channels" specifies the number of channels in the VCU. It should not appear more than once in the configuration file.	
DataMailbox	1	"DataMailbox" indicates the mailbox used by the VCU for inter-board communication. It must differ from the "AckMailbox" value. The default value is 1.	
DebugOn	0	Turns on printing of all values received in the data mailbox interrupt	
DMA	1	"DMA" specifies that the indicated channel should always use DMA.	
DmaStart	2	"DmaStart" specifies that the indicated channel should use DMA for any message larger than that specified by the second parameter (the size being in bytes).	
Event	2	"Event" specifies a routine that should be called as soon as a board receives data on the indicated channel. The first parameter is the channel, and the second parameter is the routine (the routine preferably cannot take any input argument and cannot return any value).	
GuaranteedDelivery	1	"GuaranteedDelivery" indicates that the channel will block on certain queue and pool overflows, rather than lose the message. The queue and pool overflows in question are those that are unreportable as returns to vcuSend(), vcuRecv(), or vcuFree() calls. Blocking on these overflows blocks all incoming messages for the board in question and can result in other queues and pools overflowing.	
Handlers	1	"Handlers" specifies the number of files to be included in the vcuConfig.cpp file. It should not be called twice.	
Hndlr	1	"Hndlr" specifies a file to be included in the vcuConfig.cpp file. If too many or too few files are specified, the autoConfig code declares the configuration invalid. "Hndlr" should not be specified before "Handlers".	
Includes	1	"Includes" specifies the number of files to be included in the file vculnterface.h. "Includes" should not be called more than once.	
Incl	1	"Incl" specifies a file to be included in the file vcuInterface.h. If too many or too few files are specified, the autoConfig code declares the configuration invalid. "Incl" should not be specified before "Includes".	
MailboxQueueSize	1	"MailboxQueueSize" specifies the size of the msgQ leaving the mailbox ISR. The default value is 8.	
MemPairPoolSize	1	"MemPairPoolSize" specifies the size of the memory pool for memory pairs (used in the "push" configuration types). This is a board-wide memory pool, used by all channels. The default value is 8.	

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Keyword:	Parameters:	Meaning:		
No_DMA	1	"No_DMA" specifies that the indicated channel should never use DMA.		
NoRxPool	2	"NoRxPool" specifies a channel and board where the VCU should not support receive operations. The first parameter is the channel and the second parameter is the board's system processor number. If NoRxPool is specified for any board in a channel, then the system processor numbers should be in the range of 0 to BoardCount-1.		
NoTxPool	2	"NoTxPool" specifies a channel and board where the VCU should not support transmit operations. The first parameter is the channel and the second parameter is the board's system processor number. If NoTxPool is specified for any board in a channel, then the system processor numbers should be in the range of 0 to BoardCount-1.		
PartitionAddress	1	"PartitionAddress" specifies the location of the memory partition created by the VCU for VME bus accessibility.		
PartitionFactor	1	"PartitionFactor" specifies the factor used in setting the size of the partition. Buffers used to receive data in the "push to buffer on receive" configuration type are allocated from here, so these drive the size of the partition factor. The factor also allows for fragmented allocation because of the memory alignment specified in the allocation.		
RxPoolSize	2	"RxPoolSize" specifies the size of the receiving memory pool for a channel. The first parameter is the channel, and the second parameter is the pool size. The default value is 8.		
RxQueueSize	2	"RxQueueSize" specifies the size of the receiving queue for a channel. The first parameter is the channel, and the second parameter is the queue size. The default value is 8.		
RxReplyQueueSize	1	"RxReplyQueueSize" specifies the size of the queue delivering responses from the VCU Rx Task to the vcuRecv() routine.		
RxRqstQueueSize	1	"RxRqstQueueSize" specifies the size of the queue delivering vcuRecv() requests to the VCU Rx Task.		
RxTaskCount	1	"RxTaskCount" specifies the number of tasks set aside to handle vcuRecv() calls. The first task handles all non-blocking calls, while the other tasks handle blocking calls. The minimum value should be 2 unless vcuRecv() will never be called as blocking. The default value is 4.		
SlaveWindowSize	1	"SlaveWindowSize" specifies the size of the slave windows for boards in the system. The valid options are "half" and "full", which correspond to 0x04000000 and 0x08000000. The default value is "half".		
TaskPriority	2	"TaskPriority" specifies the priority of the indicated task, "Socket", "Tx", "Rx", or "Debug". The default value is 100 for all tasks.		
TxPoolSize	2	"TxPoolSize" specifies the size of the transmitting memory pool for a channel. The first parameter is the channel, and the second parameter is the pool size. The default value is 8.		
TxReplyQueueSize	1	"TxReplyQueueSize" specifies the size of the queue that delivers update responses from the VCU Tx Task to the vcuSend() routine.		
TxRqstQueueSize	1	"TxRqstQueueSize" specifies the size of the queue that delivers vcuSend() requests to the task that actually performs the data transmission (the VCU Tx Task).		
TxStatusQueueSize	1	"TxStatusQueueSize" specifies the size of the queue that delivers status responses from the VCU Tx Task to the vcuSend() routine.		

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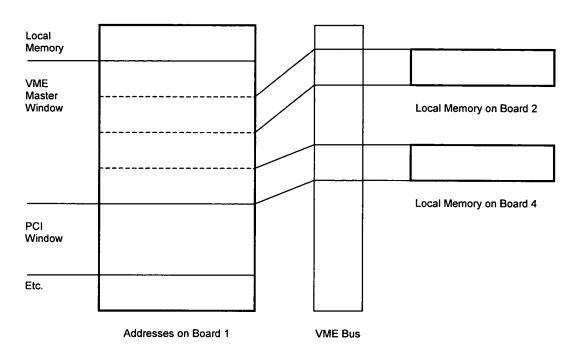


Figure 32

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Constant:	Value:	Meaning:
VCU_ERROR_NO_CODE	0x1	Mainly used internally, but also used as a return value for a multicast "vcuRequestErrno()" so this routine can be used to check whether any errors exist in the system
VCU_SUCCESS	0x2	The VCU command operated successfully
VCU_RECV_EMPTY	0x3	The non-blocking vcuRecv() command found no message.
VCU_BAD_CHANNEL	0x4	An unexpected channel was received. This can be directly, from an API call, or indirectly, from data corrupted when copied across the VME bus.
VCU_MSGQ_FULL	0x5	Used internally on a vcuSend() when the channel is configured for copy to self.
VCU_POOL_FULL	0x6	The vcuSend() or vcuRecv() call could not find sufficient memory space in the memory pool to perform the send or receive.
VCU_NO_RECV_TASK	0x7	The vcuRecv() call is a blocking call, but no task is available for a blocking receive call. To fix: configure the system to have more receive tasks.
VCU_ERR_ON_RECV	0x10000	The error occurred in a section of code responsible for receiving. The code is most likely specific to handling vcuRecv().
VCU_ERR_ON_SEND	0x20000	The error occurred in code specific to handling vcuSend().
VCU_ERR_ON_FREE	0x30000	The error occurred in code specific to handling vcuFree ().
VCU_ERR_ON_PING	0x40000	The error occurred in code specific to handling vcuPing().
VCU_ERR_ON_TEST_PAT	0x50000	The error occurred in code specific to handling vcuRequestTestPattern().
VCU_ERR_ON_CONFIG	0x60000	The error occurred at initialization
VCU_ERR_ON_ERRNO	0x70000	The error occurred in code specific to handling vcuRequestErrno(). These error numbers are not stored, so that stored errors can be differentiated from errors that occur at the time of the request
VCU_ERR_IN_SOCKET	0x01000	The error occurred in code in VcuSocket.cpp.
VCU_ERR_IN_RXQUEUE	0x02000	The error occurred during an RxQueues method.
VCU_ERR_IN_MAILBOX	0x03000	The error occurred in mailbox management, in the file VcuMailbox.cpp.
VCU_ERR_IN_INTERFACE	0x04000	The error occurred in the interface to the vcuSocket, in VcuComm.cpp.
VCU_ERR_IN_RX_TASK	0x05000	The error occurred in code in VcuComm.cpp in logic specific to Rx Task management.
VCU_ERR_IN_TX_TASK	0x06000	The error occurred in code in VcuComm.cpp in logic specific to Tx Task management.
VCU_ERR_IN_VME_COPY	0x07000	The error occurred in code responsible for copying data across the VME bus.
VCU_ERR_IN_RXPOOL	0x08000	The error occurred in a RxPools method.
VCU_ERR_IN_TXPOOL	0x09000	The error occurred in a TxPools method.
VCU_ERR_IN_PAIRPOOL	0x0a000	The error occurred in a MemPairPool method.
VCU_ERR_IN_ACK	0x0b000	The error occurred in code responsible for handling an automatic acknowledgement.

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Constant:	Value:	Meaning:
VCU_ERR_NO_MEMORY	0x00010	The error occurred when requested memory is unavailable.
VCU_ERR_MSGQ_RECV	0x00020	The error occurred while trying to receive from a msgQ.
VCU_ERR_DATA_SYNCH	0x00030	The error occurred when VcuSocket tried to free a memory pool slot already freed or during RequestDataPush() when the incorrect identifier came back. The latter requires rewriting the Push communication protocol.
VCU_ERR_INTERNAL	0x00040	The error occurred when the flow reached a section of code it should not have reached.
VCU_ERR_BAD_POOL_SLOT	0x00050	The error occurred when the VcuSocket tried to Free() memory that did not come from the pool specified.
VCU_ERR_BAD_MAILBOX	0x00060	The error occurred when the VcuSocket tried to TriggerRemoteBoard() to itself or a destination outside the system boundaries.
VCU_ERR_BAD_MCAST	0x00070	The error occurred because the VCU was reconfigured so that the destinations are not specified bitwise, or a multicast was attempted on a channel configured for updating ("push")
VCU_ERR_UNLOCK_FAILED	0x00080	The error occurred during Update() when the system was unable to unlock a memory slot it just locked. This should never occur.
VCU_ERR_MSGQ_FULL	0x00090	The error occurred when a send to a msgQ found the msgQ full.
VCU_ERR_MSGQ_SEND	0x000a0	The error occurred while trying to send to a msgQ. The error is not a full msgQ error.
VCU_ERR_BAD_CONFIG	0x000b0	The error occurred when the VCU tables were in conflict with the kernel configuration.
VCU_ERR_TRIG_FAILED	0x000c0	The error should only occur when automatic acknowledgement is enabled. The error means that the automatic ack was not received. vcuPing() can be tried to make sure that the board is accessible. The return value is VCU_SUCCESS for a successful vcuPing().
VCU_ERR_MSG_TOO_BIG	0x000d0	The error occurred when the size of the message was larger than the capacity of the channel.
VCU_ERR_DEST_INVALID	0x000e0	The error occurred when a vcuPing() or vcuRequestTestPattern() found an invalid destination specified.
VCU_ERR_TASK_DIED	0x000f0	The error occurred when a receive task is found to be inaccessible.
VCU_ERR_VME_DMA	0x00100	The error occurred when a sysVmeDmaCopy() returned an error value.
VCU_ERR_ISR_USE	0x00200	The error occurred when vcuSend() was called from an ISR.
VCU_MBOX_FULL_QUEUE	0xff	The error occurred when the receiver's mailbox ISR found its outgoin msgQ full. The message is lost, but the sender gets an error message.
VCU_MBOX_QUEUE_ERROR	0xfe	The error occurred when the receiver's mailbox ISR found its outgoing msgQ broken (not just full). The message is lost, but the sender gets an error message. All further messages are likely to get the same response.

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## Application

## vcuSend()

Call vcuSocket.SendToSelf().

- Enqueue message in the Rx pool
- Return status

Return status

Figure 34: The sending sequence for the "Queue to self" configuration.

## Application

## vcuRecv()

Call vcuSocket.Recv()

- Receive from the vcuSocket queue, based on the channel.
- Copy the data into the location specified in the calling argument.
- Write the message size into the calling argument.
- Return status

Return status

Figure 35: The receiving sequence for the "Queue to self" configuration

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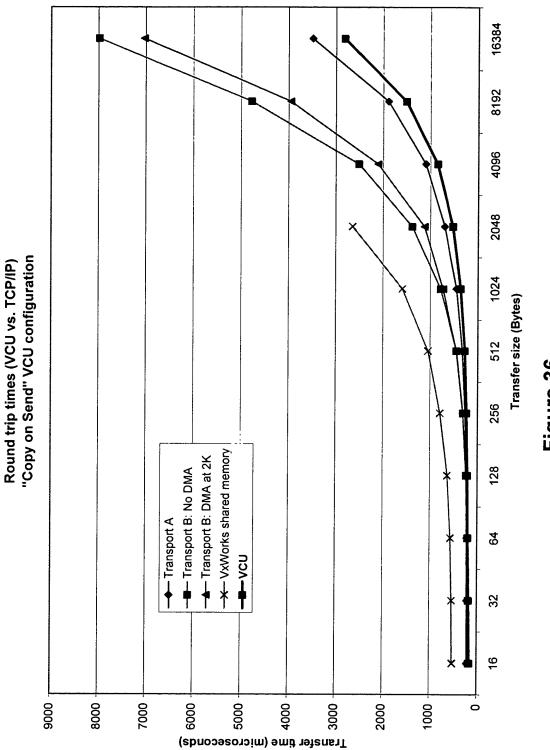
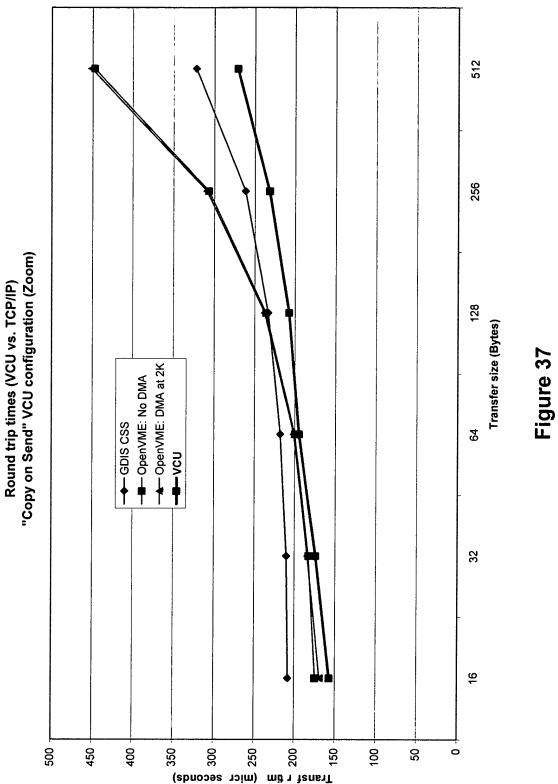


Figure 36

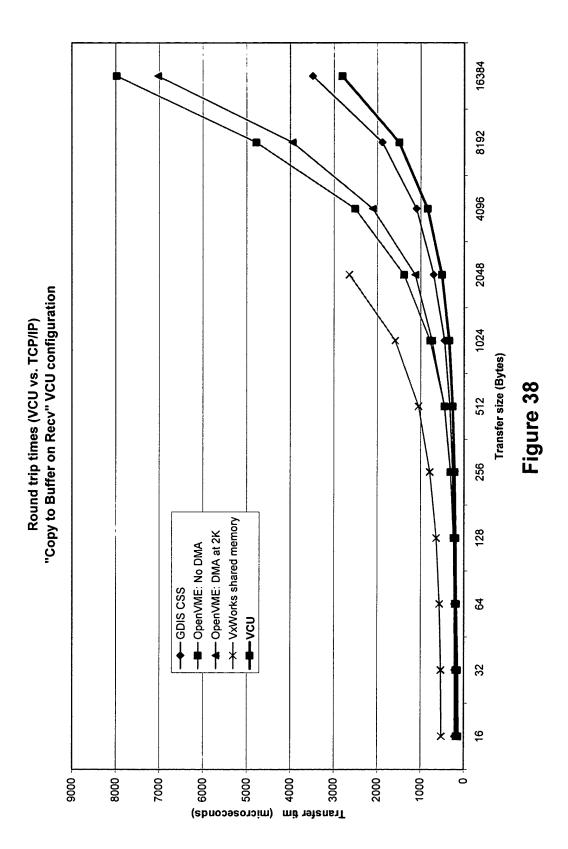
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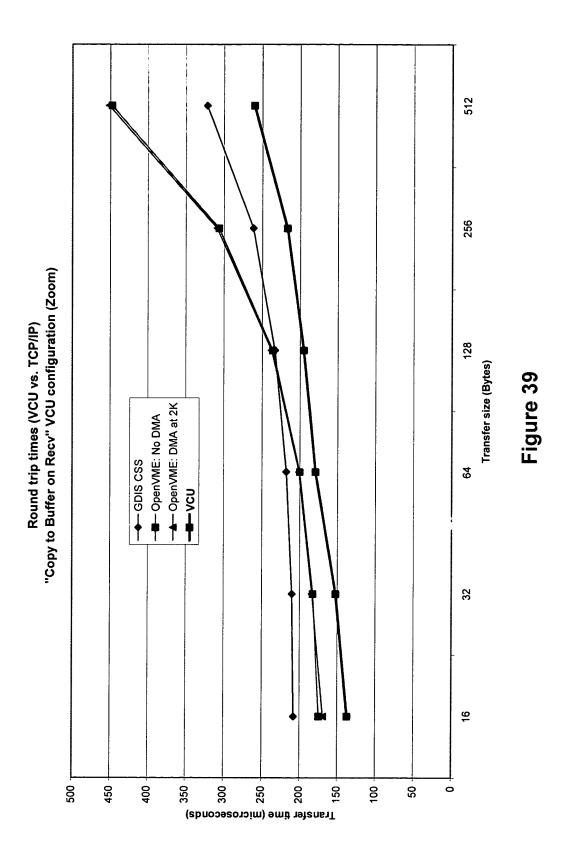
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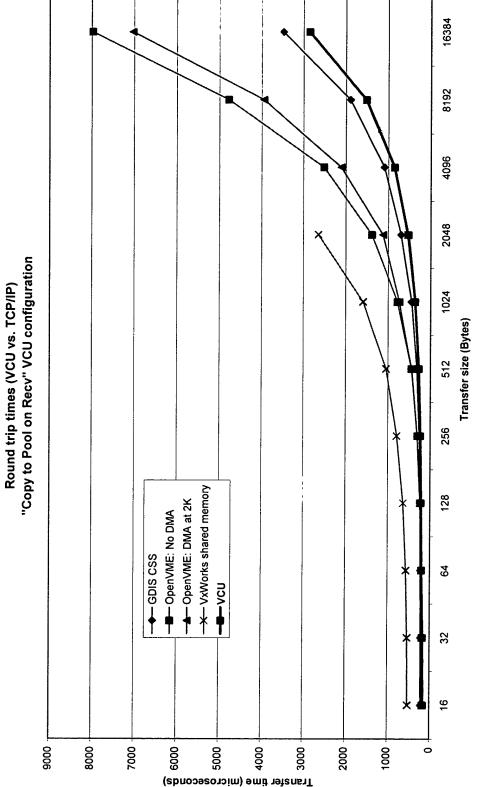
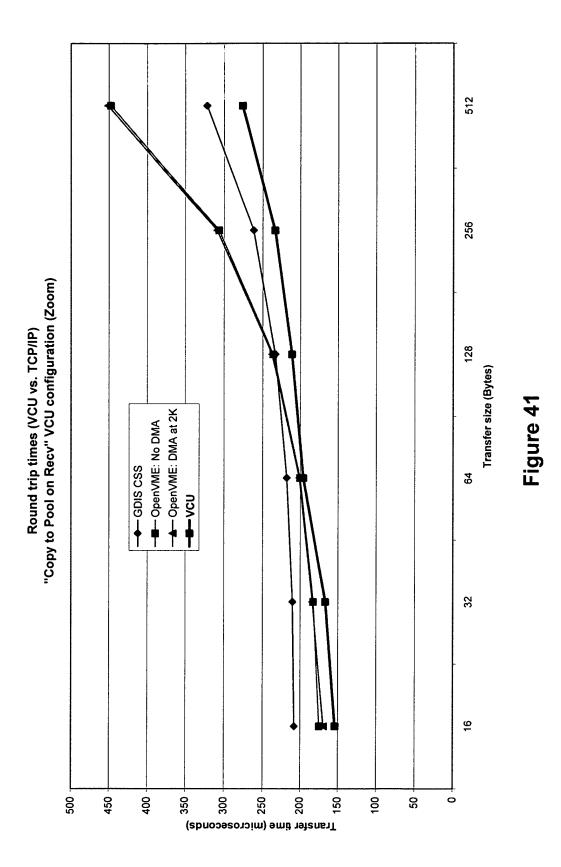


Figure 40

Title: Method And Apparatus For Communicating Data Over A Bus According To Redefinable Configurations

Inventor(s): Winkeler et al.
Express Mail. No. EV328618105US
Docket # 66638/40337



Method And Apparatus For Communicating Data Over A Bus According To Redefinable Configurations Title:

Inventor(s): Winkeler et al. Express Mail. No. EV328618105US Docket # 66638/40337



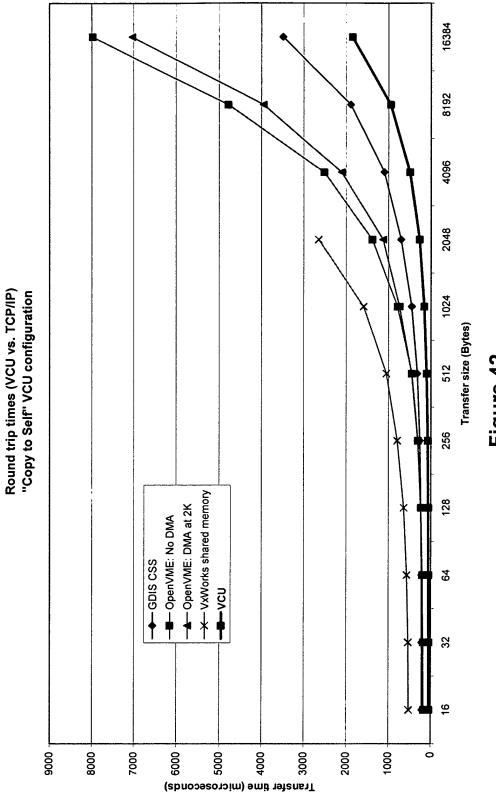
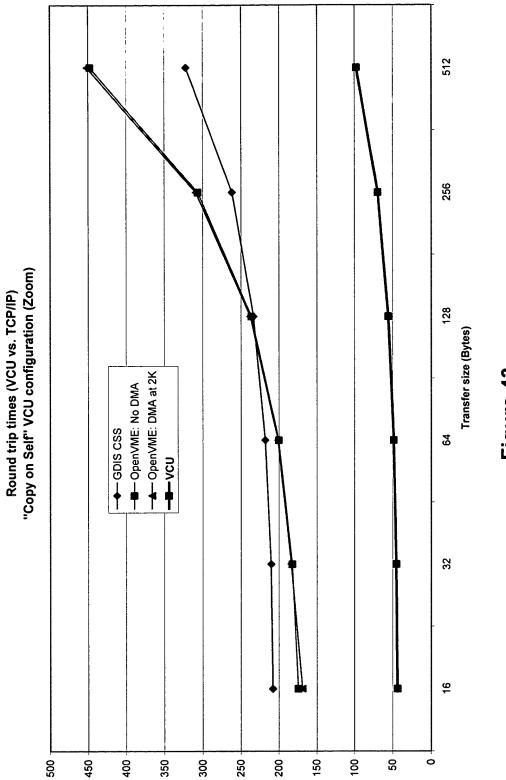


Figure 42

Method And Apparatus For Communicating Data Over A Bus According To Redefinable Configurations

Inventor(s): Winkeler et al. Express Mail. No. EV328618105US Docket # 66638/40337

50/54



Transfer time (microseconds)

Figure 43

Method And Apparatus For Communicating Data Over A Bus According To Redefinable Configurations Title:

Inventor(s): Winkeler et al. Express Mail. No. EV328618105US Docket # 66638/40337



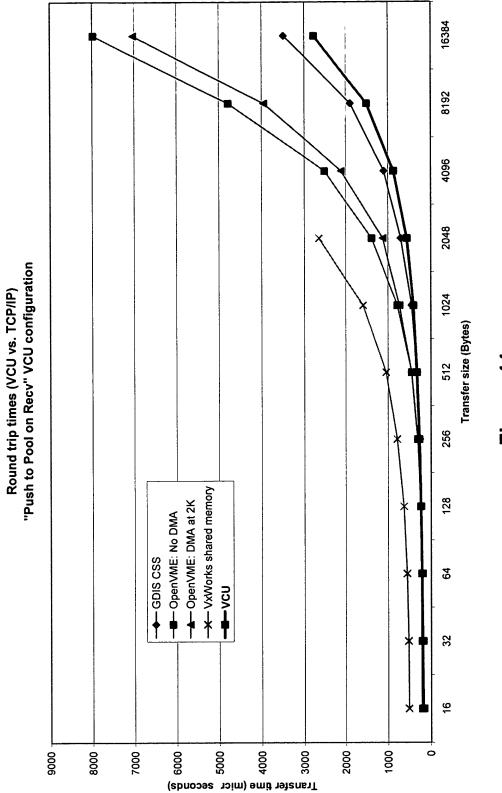
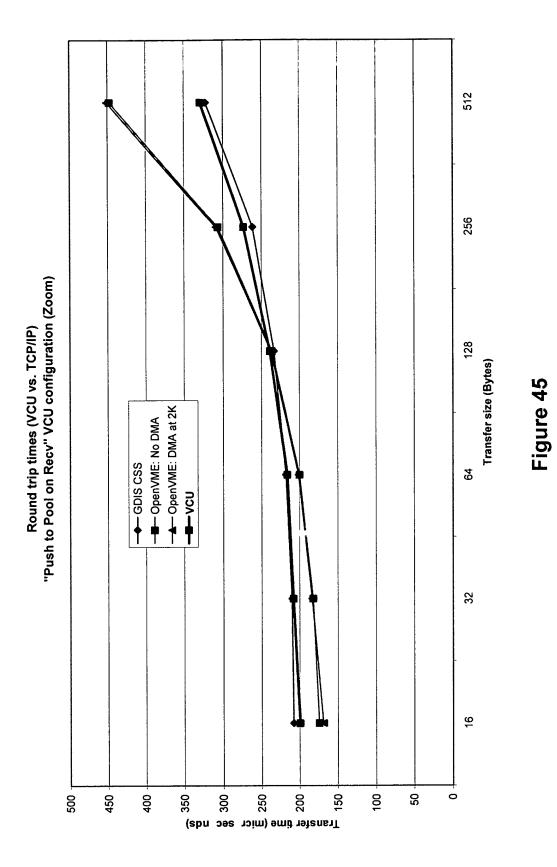


Figure 44

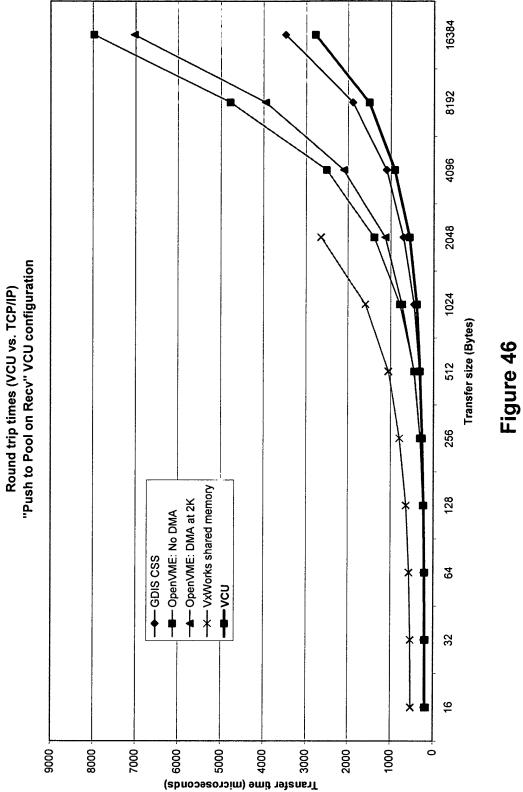
Title: Method And Apparatus For Communicating Data Over A Bus According To Redefinable Configurations
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